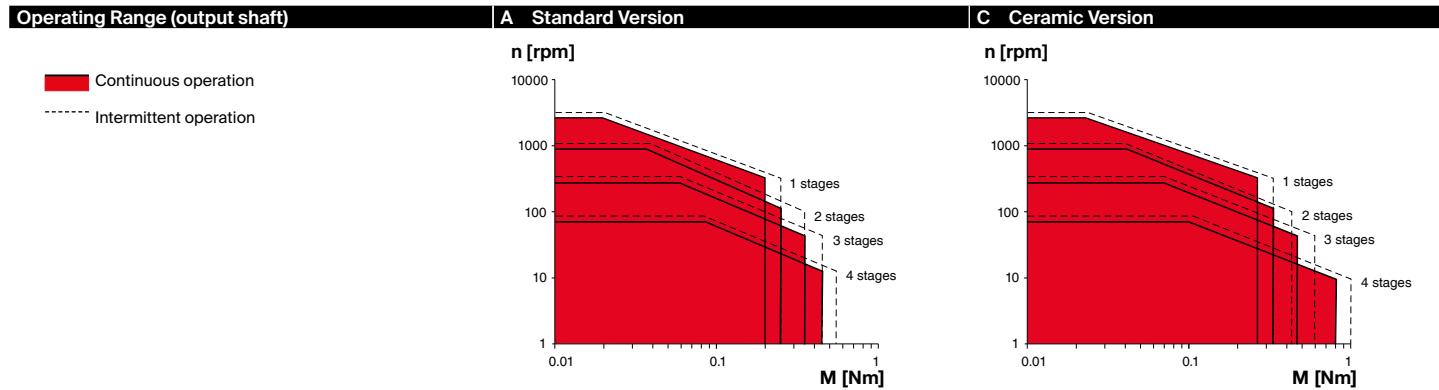


GPX 16 Ø16 mm, planetary gearbox



GPX

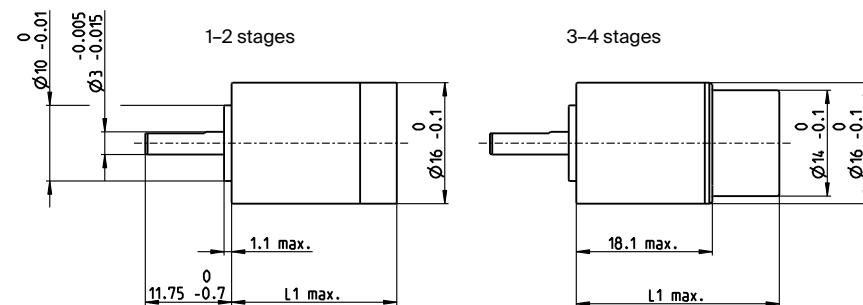
Key Data		A Standard Version	C Ceramic Version
Max. transmittable power	W	6.5	7.8
Max. continuous torque	Nm	0.45	0.6
Max. continuous input speed	rpm	16000	16000
Ambient temperature	°C	-40 ... +100	-40 ... +100
Bearing at output		Ball bearing	Ball bearing



Specifications		A Standard Version	C Ceramic Version
Number of stages		1 2 3 4	1 2 3 4
Max. transmittable continuous power	W	6.5 3.2 1.6 0.60	7.8 3.8 1.9 0.7
Max. transmittable intermittent power	W	8.0 4.0 2.0 0.75	10.0 5.0 2.5 1.0
Max. continuous torque	Nm	0.20 0.25 0.35 0.45	0.27 0.33 0.47 0.60
Max. intermittent torque	Nm	0.25 0.35 0.45 0.55	0.33 0.42 0.58 0.75
Max. continuous input speed	rpm	12000 14000 16000 16000	12000 14000 16000 16000
Max. intermittent input speed	rpm	15000 17500 20000 20000	15000 17500 20000 20000
Max. efficiency	%	90 80 75 65	90 80 75 65
Average backlash no load	°	1.0 1.2 1.3 1.4	1.0 1.2 1.3 1.4
Max. axial load (dynamic)	N	20 20 20 20	20 20 20 20
Max. radial load, 5 mm from flange	N	30 45 70 70	30 45 70 70
Gearhead length L1 ¹	mm	15.8 20.7 25.7 30.6	15.8 20.7 25.7 30.6
Weight	g	20 25 27 31	20 25 27 31

Configuration		A Standard Version	C Ceramic Version
Number of stages		1 2 3 4	1 2 3 4
Reduction	X:1	3.9, 5.3, 6.6 16, 21, 26, 28, 35, 44	3.9, 5.3, 6.6 16, 21, 26, 28, 35, 44
Absolute reduction: (see online)		62, 83, 103, 111, 138, 150, 172, 186, 231	62, 83, 103, 111, 138, 150, 172, 186, 231
Version	Standard/ceramic version/noise reduced/reduced backlash/high power		
Flange	Standard flange/configurable flange		
Shaft	Length/flat face		

maxon Modular System		Page	Dimensions	M 1:1
maxon DC motor	Nº of stages [opt.]			
DCX 14 L	3-4	91-92		
DCX 16 S	1-2 [3-4]	93-94		
DCX 16 L	1-2 [3-4]	95-96		
DC-max 16 S*	1-2 [3-4]	109-110		
maxon EC motor	Nº of stages [opt.]			
ECX SPEED 13 M	3-4	187-188		
ECX SPEED 13 L	3-4	191-192		
ECX SPEED 16 M	1-2 [3-4]	195-196		
ECX SPEED 16 L	1-2 [3-4]	199-200		



*Limited selection of reduction ratios
(see online).

¹This length may vary depending on the configuration and choice of motor. The effective length is calculated at the end of the configuration process.

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