

## Summary

- Converter for driving permanent-magnet synchronous motors (PMSM) and brushless DC motors (BLDC)
- Sensorless speed control from 5,000 rpm up to 500,000 rpm
- Maximum output power: 1,000 W
- Separate supply for power and digital part
- No output filter required
- User definable setup for different motor parameters
- Torque and speed control
- Highest possible efficiency
- Integrated break chopper up to 2 W
- Optional external break chopper up to 420 W
- Parallel connection of several converters to one DC-bus possible
- User-friendly PC control software (CelerotonPilot)

## Specifications

Input voltage power part $U_{in}$ (DC)	24 – 100 V
Input voltage digital part $U_{in}$ (DC)	24 V
Maximum output power (with respective cooling)	1,000 W
Output voltage (peak value phase-phase)	0 – 0.93 $U_{in}$
Maximum phase current (PAM-operation)	8.7 Arms / 12.3 Apeak <sup>1</sup>
Maximum frequency / speed (PAM-operation)	8.3 kHz / 500,000 rpm
Operating range motor	4-Quadrant
Communication interface	USB
Communication interfaces (switchable)	RS232, CAN
PC control software	CelerotonPilot
Weight	0.28 kg
Dimensions (L x W x H)	195 x 125 x 24 mm
Operating temperature	0 – 40 °C

<sup>1</sup>Fundamental of the PAM-block current

## Interfaces

### Connector X8 – in-/output (6 Pin)

1 x Analog input	0 – 10 V
1 x Analog output	0 – 10 V
1 x Temperature measurement input	PTC or NTC, resistance range according to option Tx
2 x GND	
1 x Auxiliary power supply	10 V, 100 mA

### Connector X7 – in-/output (8 Pin)

1 x COM	Common rail for digital outputs	
3 x Digital outputs	0 – 24 V (Relay, normally open contacts)	
2 x GND		
2 x Digital inputs	0 – 4 V 10 – 24 V	Low level High level

## Options

### CC-100-1000.**SLx.Tx**

#### Sensorless **SLx**

- **SL1 (Standard):**
  - o Speed constants between 550 and 18,250 rpm/V
  - o Sensorless speed control from 7,000 rpm
- **SL2:**
  - o Speed constants between 400 and 7,900 rpm/V
  - o Sensorless speed control from 5,000 rpm

The stated values are valid for number of pole pairs p=1. For higher number of pole pairs the speed constant and minimum speed are divided by the number of pole pairs p.

#### PTC/NTC **Tx**

- **T1 (Standard):** Measurement range 6-150 Ω, e.g. PT100
- **T2:** Measurement range 0.26-86 kΩ, e.g. KTY84, NTC10k

## Accessories

- Connector set CC-100-1000

## Operating range

The operating range of the converter is dependent on the output voltage ( $U_{out}$ ) (peak value phase-phase) in Figure 1. The output power ( $P_{out}$ ) increases with the output voltage as the phase current ( $i_{ph}$ ) (rms) is constant until the power limit is reached. Above that point  $i_{ph}$  decreases with increasing output voltage. The input voltage ( $U_{in}$ ) (grey area) must be higher than the maximum required output voltage.

Operating with full output power of 1,000 W requires cooling with heat sink with thermal resistance  $R_{th} \leq 1 \text{ K/W}$ . Without heat sink a maximum phase current of 2.3 A and maximum output power of 280 W is available.

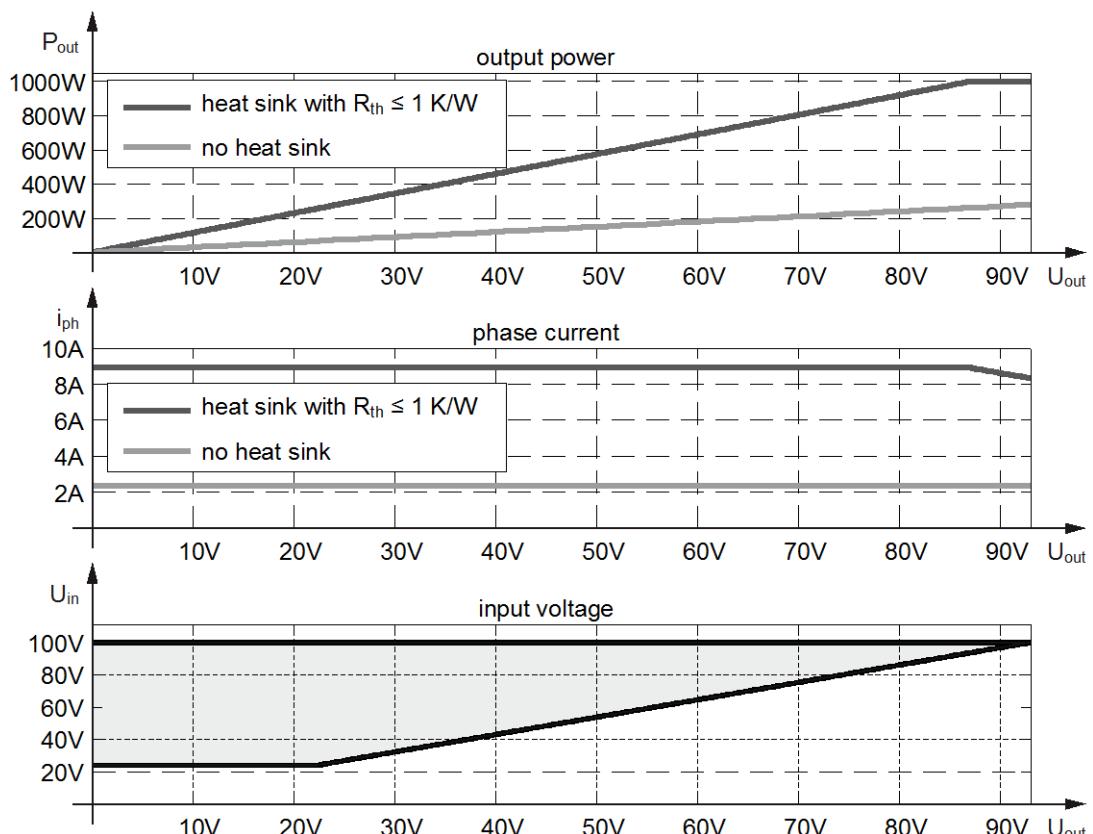
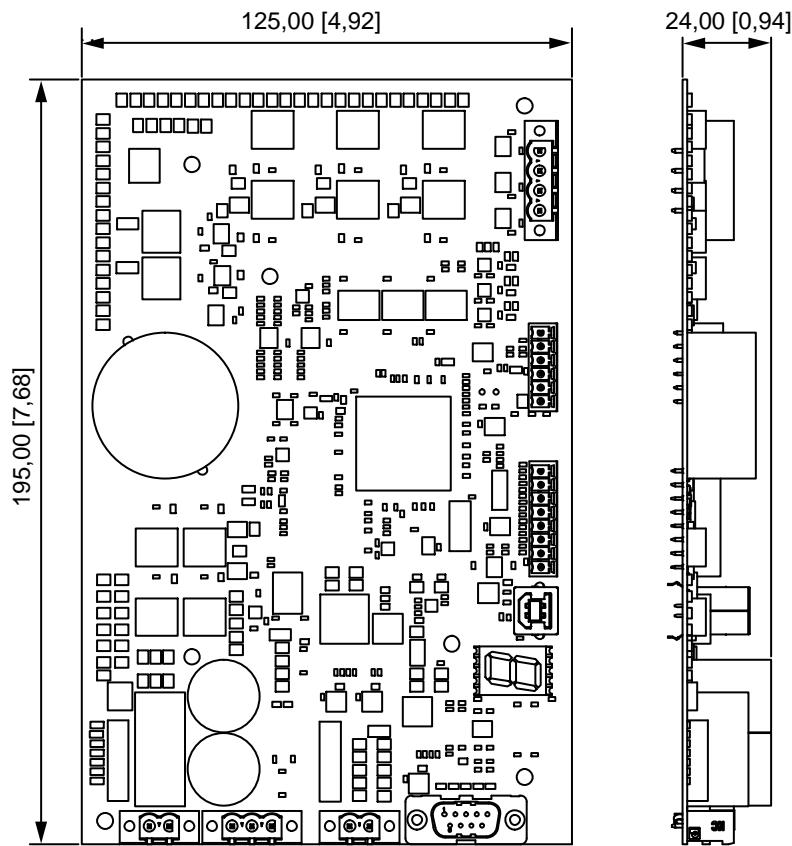


Figure 1: Output power, phase current and input voltage range of the converter CC-100-1000.

## Dimensions in mm [inch]



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