

CC-75-400



Summary

- Converter for driving permanent-magnet synchronous motors (PMSM) and brushless DC motors (BLDC)
- Sensorless speed control from 5,000 rpm up to 500,000 rpm
- Maximum output power of 400 W
- No output filter required
- User definable setup for different motor parameters
- Torque- and speed-control
- Highest possible efficiency
- Integrated braking chopper
- Mountable on a DIN-rail
- Parallel connection of several converters to one DC-bus possible
- User-friendly PC control software (CelerotonPilot)

Specifications

| | |
|---|-----------------------------------|
| Input voltage U_{in} (DC) | 24 – 75 V |
| Maximum output power | 400 W |
| Output voltage (peak value phase-phase) | 0 – 0.95 U_{in} |
| Maximum phase current (PAM-operation) | 4.7 Arms / 6.6 Apeak ¹ |
| Maximum frequency / speed | 8.3 kHz / 500,000 rpm |
| Operating range | 4-Quadrant |
| Communication interface | USB |
| Communication interface (optional) | RS232, RS485, CAN |
| PC control software | CelerotonPilot |
| Weight | 0.5 kg |
| Dimensions | 150 x 95 x 35 mm |
| Operating temperature | 0 – 40 °C |

¹Fundamental of the PAM-block current

I/O connections

| Connector X2 – I/O interface (6 pins) | |
|---------------------------------------|---|
| 1 x analog input | 0 – 10 V |
| 1 x analog output | 0 – 10 V |
| 1 x temperature measurement input | Thermocouple type K |
| 1 x temperature measurement input | PTC or NTC, resistance range according to option Tx |
| 1 x GND | |
| 1 x power supply | 10 V, 200 mA |

| Connector X3 – I/O interface (6 pins) | |
|---------------------------------------|---|
| 1 x COM | Common rail for digital outputs |
| 2 x digital outputs | 0 – 24 V (relay, normally open contacts) |
| 1x GND | |
| 2 x digital inputs | 0 – 24 V (software adjustable thresholds 0.8 – 23 V) |

Options

CC-75-400.SLx.COx.Tx

Sensorless SLx

- **SL1 (Standard):**
 - o Speed constants between 550 and 18,250 rpm/V
 - o Sensorless speed control from 7,000 rpm
- **SL2:**
 - o Speed constants between 400 and 7,900 rpm/V
 - o Sensorless speed control from 5,000 rpm

The stated values are valid for number of pole pairs $p=1$. For higher number of pole pairs the speed constants and minimum speeds are divided by the number of pole pairs p .

Communication interfaces COx

| | USB | CAN | RS232/RS485 |
|-----------------------|-----|-----|-------------|
| CO1 (Standard) | x | | |
| CO2 | x | x | |
| CO3 | x | | x |
| | | | |

PTC/NTC Tx

- **T1 (Standard):** Measurement range 6-150 Ω , e.g. PT100
- **T2:** Measurement range 0.26-86 k Ω , e.g. KTY84, NTC10k

Accessories

- Connector set CC-75-400

Operating range

The operating range of the converter is dependent on the output voltage (U_{out}) (peak value phase-phase) in Figure 1. The output power (P_{out}) increases with the output voltage as the phase current (i_{ph}) is constant until the power limit is reached. Above that point i_{ph} decreases with increasing output voltage. The input voltage (U_{in}) (grey area) must be higher than the maximum required output voltage.

The maximum output power (P_{out}) of the converter CC-75-400 depends on the ambient temperature (T_{amb}). The average power losses in the braking chopper ($P_{chopper}$) are limited by the output power and the ambient temperature. The respective relation is depicted in Figure 2.

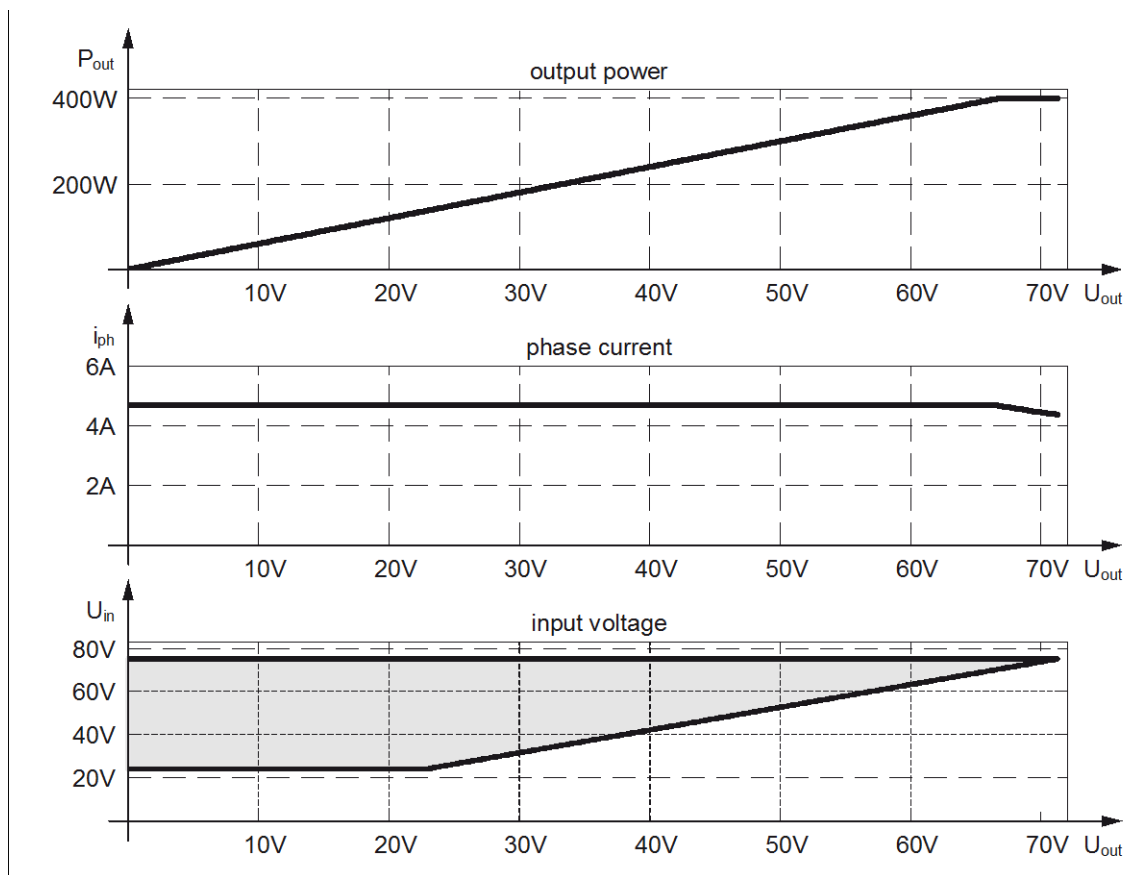


Figure 1: Output power, phase current and input voltage range of the converter CC-75-400.

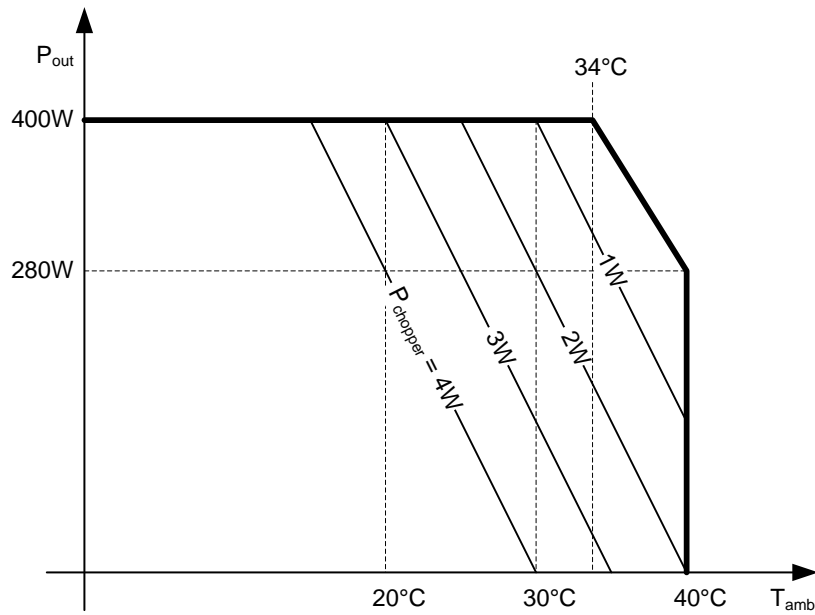
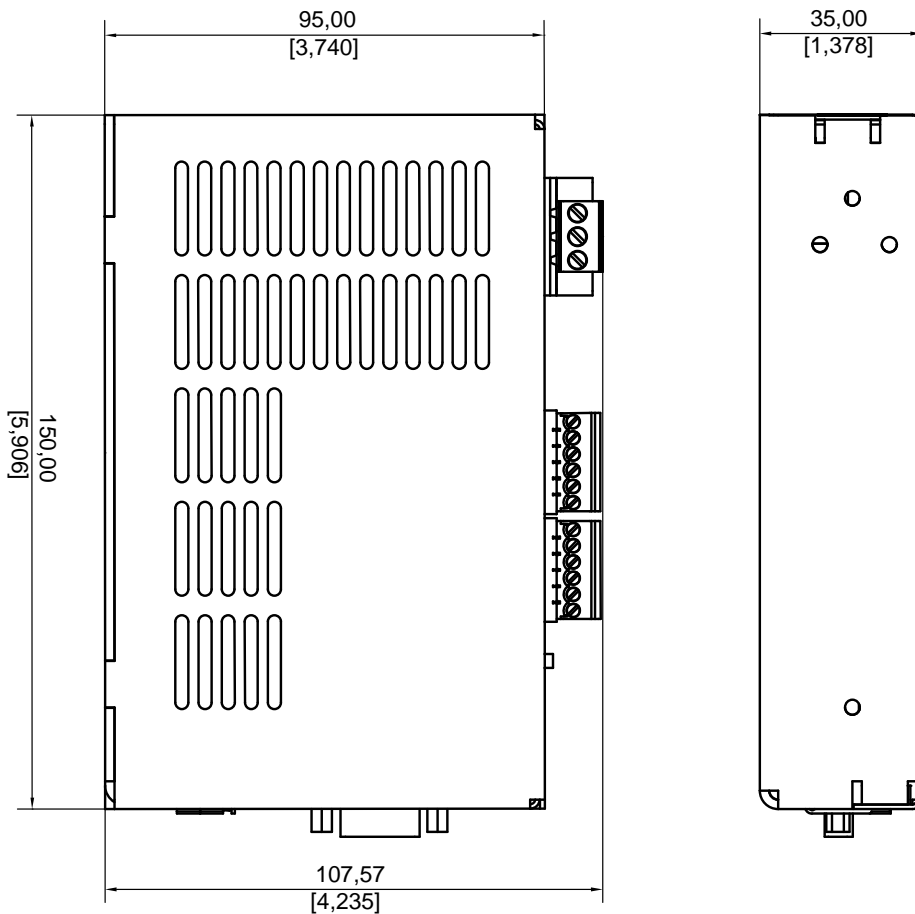


Figure 2: Safe operating area (SOA) of the converter CC-75-400 versus ambient temperature (T_{amb}) and the allowed average power losses in the braking chopper ($P_{chopper}$).

Dimensions in mm [inch]



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